
[IEEE Transactions on Robot Learning](#) [1]

Online_ISSN:

3070-1120

Disciplina:

Robotics and Control Systems/ Computing and Processing/ Components Circuits Devices and Systems

OASubject:

- [Physical Sciences & Engineering](#) [2]

OA Type:

- [Hybrid OA](#) [3]

Publisher:

- [IEEE](#) [4]

Source URL: <https://biblio.unipi.it/ru/ieee-transactions-robot-learning>

Links

[1] <https://biblio.unipi.it/ru/ieee-transactions-robot-learning> [2] <https://biblio.unipi.it/ru/open-access-e-open-science-0/elenco-delle-pubblicazioni-oa/404> [3] <https://biblio.unipi.it/ru/oa-tipologia/hybrid-oa> [4] <https://biblio.unipi.it/ru/oapublisher/ieee>